Scaling Distributed Machine Learning with In-Network Aggregation

Jacob Nelson with

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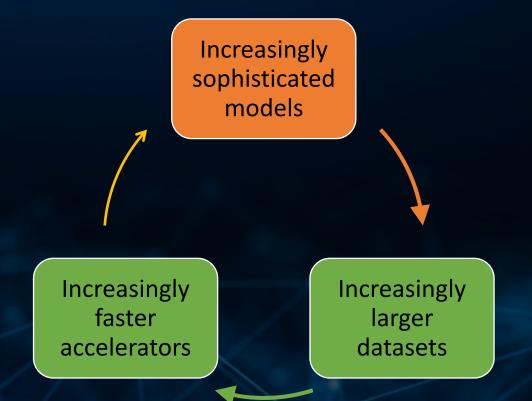








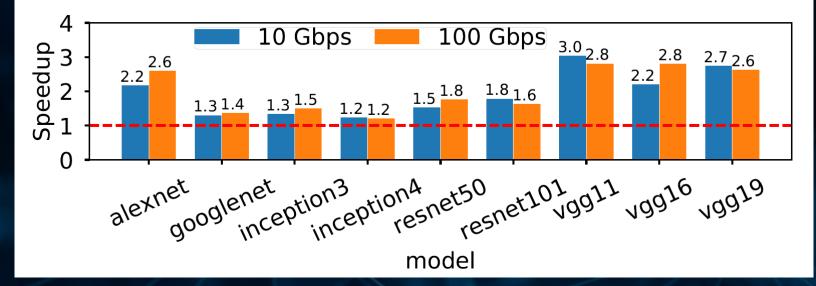




Innovation fueled by leaps in (costly) infrastructure: Clusters with hundreds of machines, each with many HW accelerators (GPUs)

Training models is still time-consuming: hours, days or even weeks!

Scaling Machine Learning

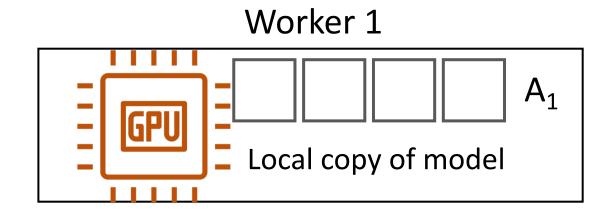


Can the network be the ML accelerator?

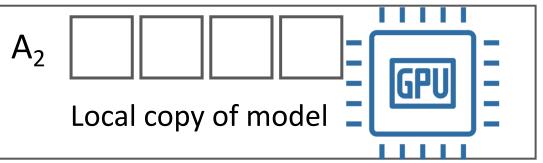
Outline

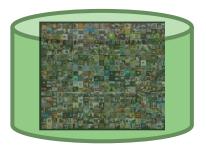
- The distributed training process
- In-network aggregation design
- Evaluation
- Future work and conclusion

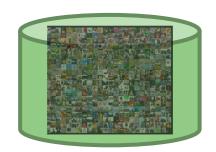
Data-parallel distributed training



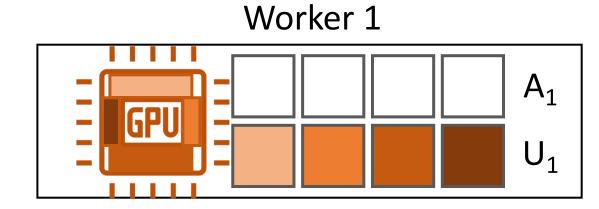




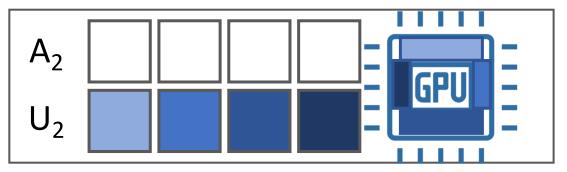




Phase 1: Workers learn independently



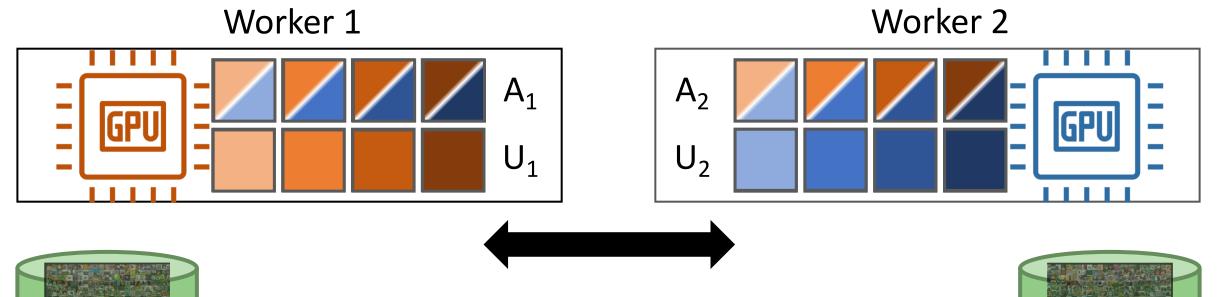
Worker 2





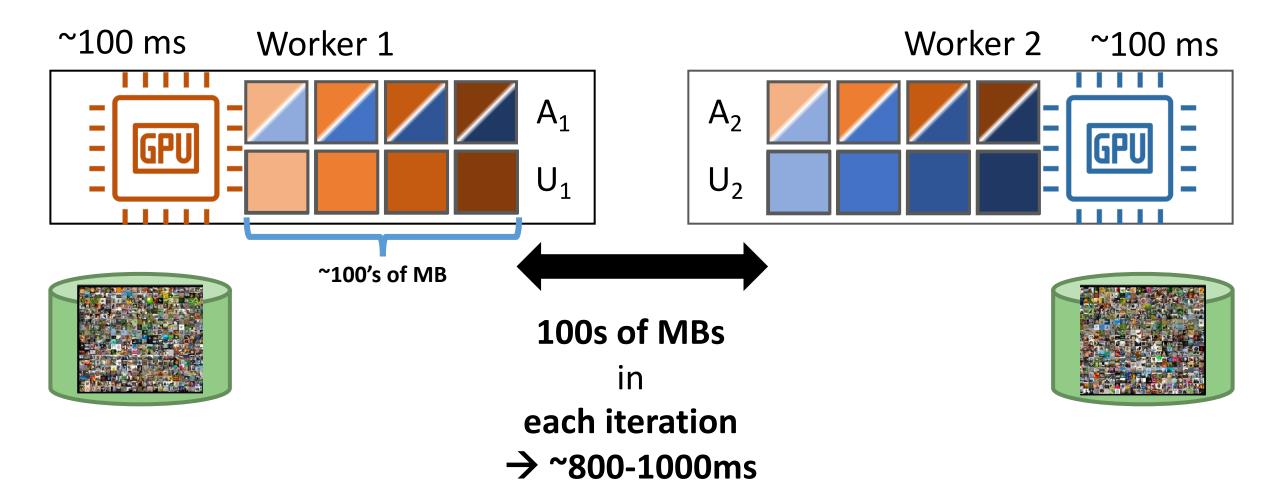


Phase 2: Workers exchange what they've learned

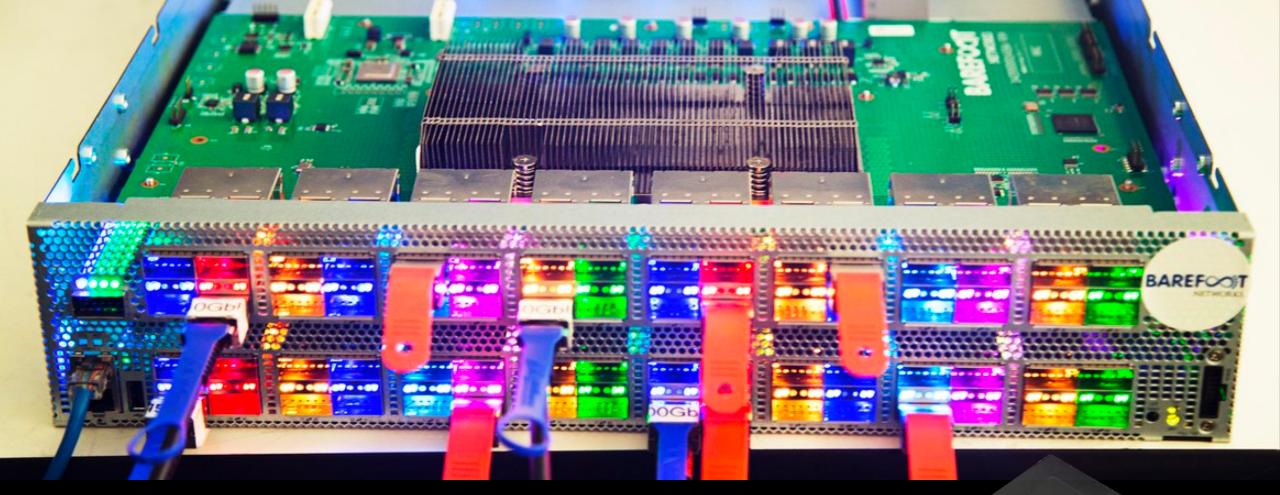




Aggregation is communication-intensive



Aggregation is communication-intensive If only I could sh training **Problem:** help... **ortieneck** to the Intensive, all-to-all network! communication! . . . Worker N updates Worker 1 updates Worker 2 updates

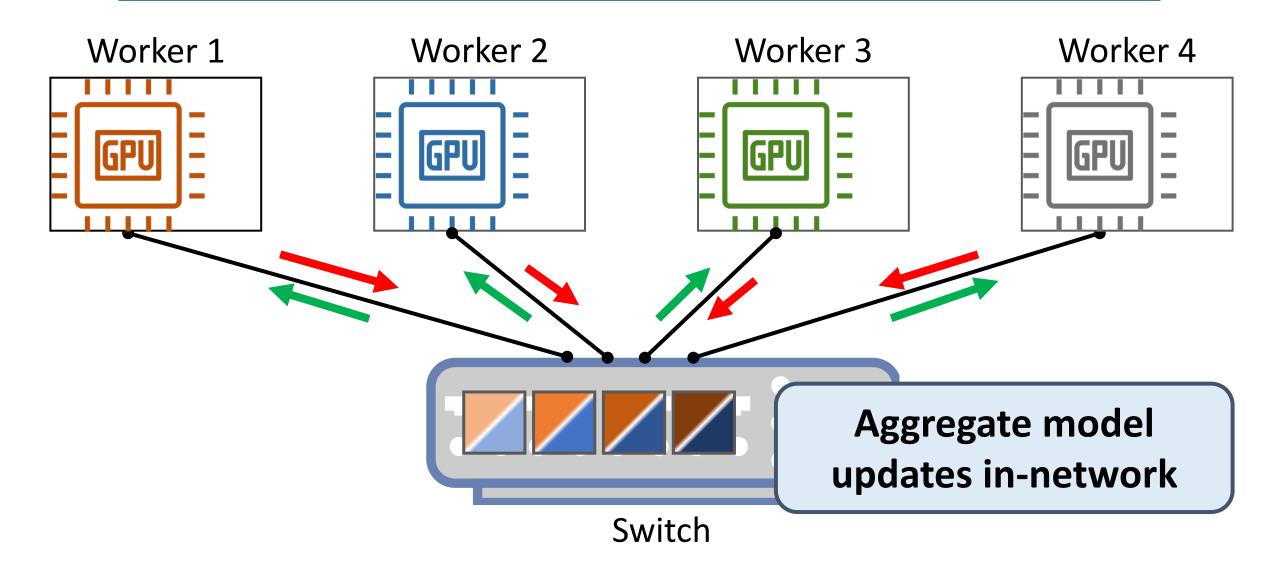


Programmable data plane switches to the rescue!

100 Gbps line rate processing

6.5 Tbps

SwitchML: the network is the ML accelerator



Co-design ML and networking for efficiency

Challenges

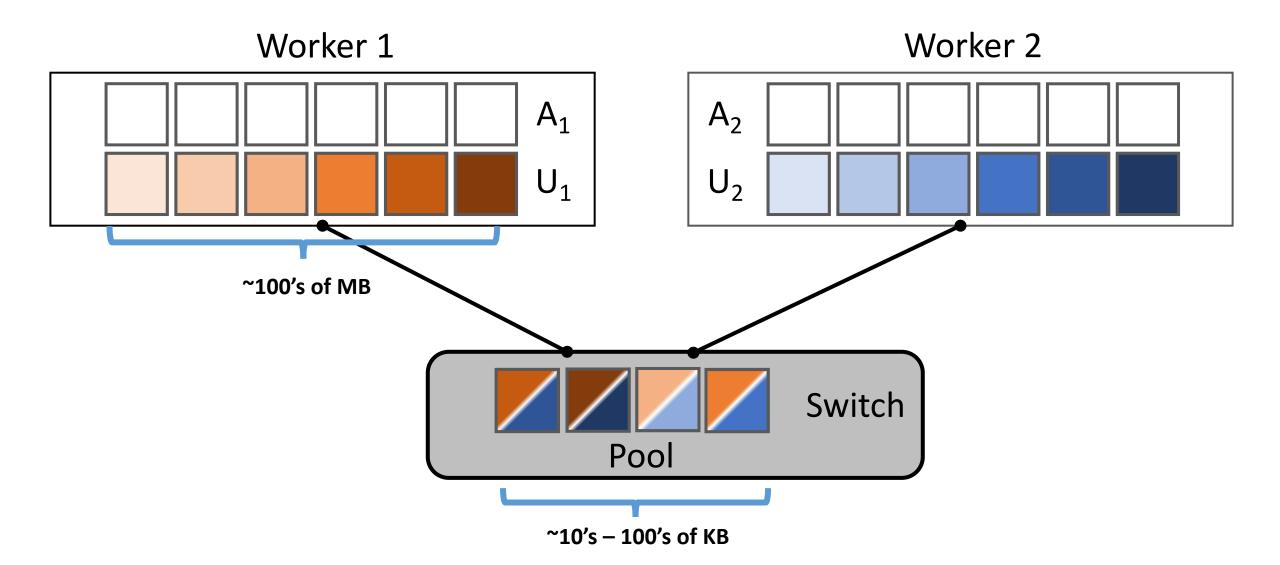
- </>
 Limited storage
 - Limited computation
 - No floating point
 - Packet loss

Design

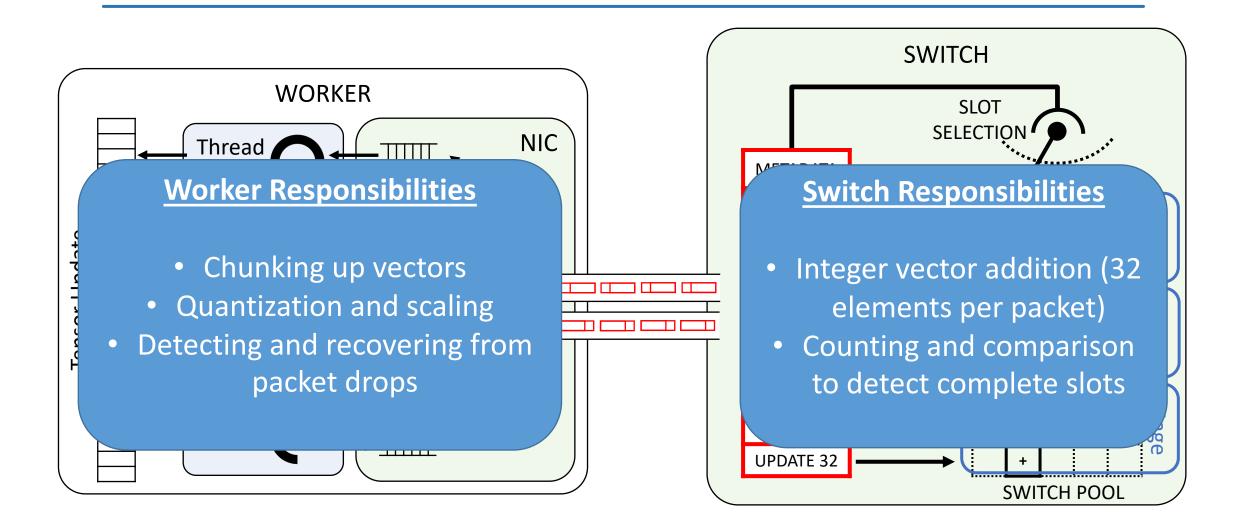
- Pool-based streaming aggregation
- Combined switch-host architecture
- Quantized integer operations
- Failure-recovery protocol

6.5 Tbps programmable data plane

Streaming aggregation with a pool



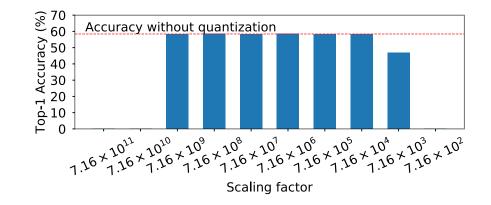
Combined switch-host architecture



Quantization

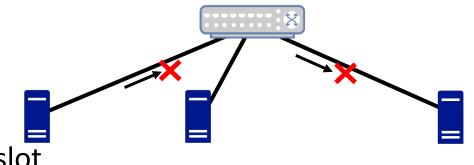
- Convert floating point to 32-bit fixed-point values
- Updates are scaled by multiplying for a scaling factor sf
- $\widetilde{U_j^i} = round(sf * U_j^i)$ $\widetilde{A_j^i} = A_j^i/sf$
- Approach 1: (restricted) 16-bit floating point ↔ 32-bit fixed point conversion
 → Directly in the switch
- Approach 2: 32-bit floating point ↔ 32-bit fixed point conversion
 → At workers with AVX instructions
 With single scaling factor obtained by profiling

This quantization allows training to similar accuracy in a similar number of iterations as an unquantized network for a large range of scaling factors



Packet loss tolerance

- Packet loss can happen in two directions
- Workers detect losses using timers
- Lost packets are retransmitted
 - A model update must not be applied twice
 - A model update must not be applied to a "full" slot



- Workers' per-slot contributions tracked with a bitmap
 - Ignores duplicates
- Shadow copy of the previous result for a slot
 - Retransmits a dropped result packet

Implementation

• Switch program written in P4 for Barefoot Tofino



- End-host C++ library providing a familiar all-reduce API
 - Kernel bypass



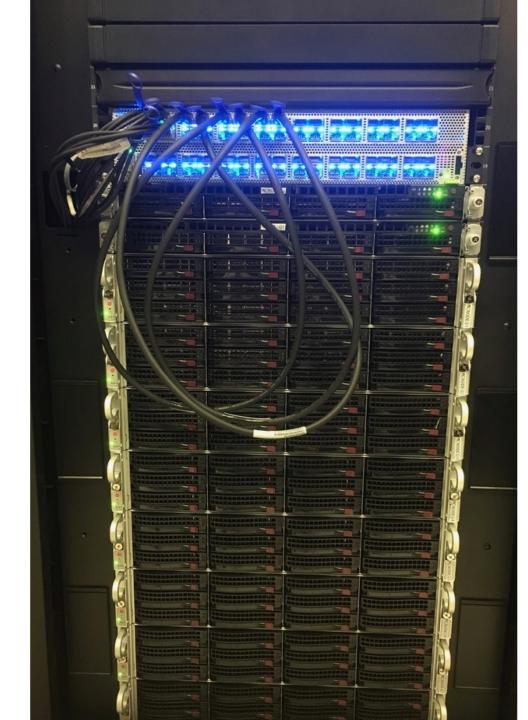
- We have integrated SwitchML with:
 - TensorFlow using Horovod,
 - PyTorch/Caffe2 using Gloo



Evaluation

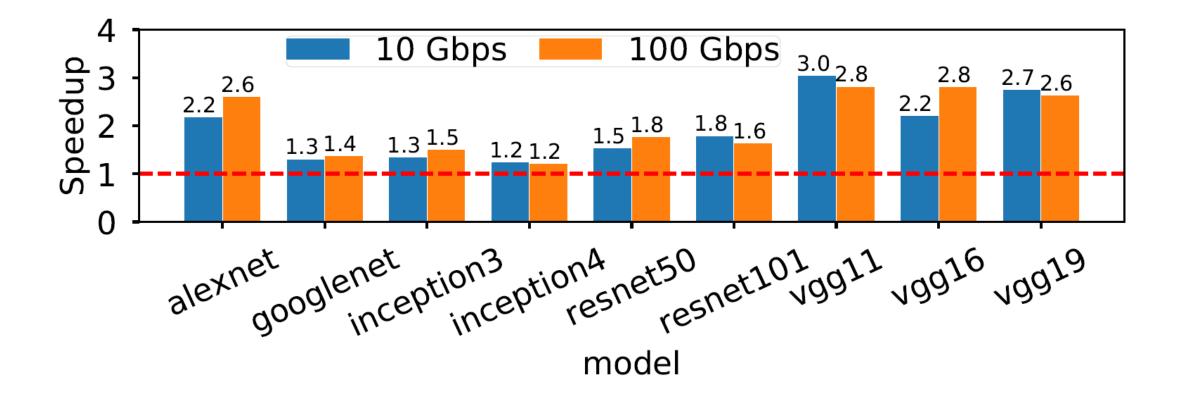
Testbed:

- 16 servers (8 w/ P100 GPUs)
 10 Gbps (Intel 82599ES)
 100 Gbps (Mellanox Connect-X 5)
- 64 x 100 Gbps switch (Barefoot Tofino)
- Models:
 - 9 standard CNN benchmarks
 - Training on ImageNet (except synthetic data with AlexNet)
 - Compared with TensorFlow using the Nvidia Collective Comm. Library (NCCL)



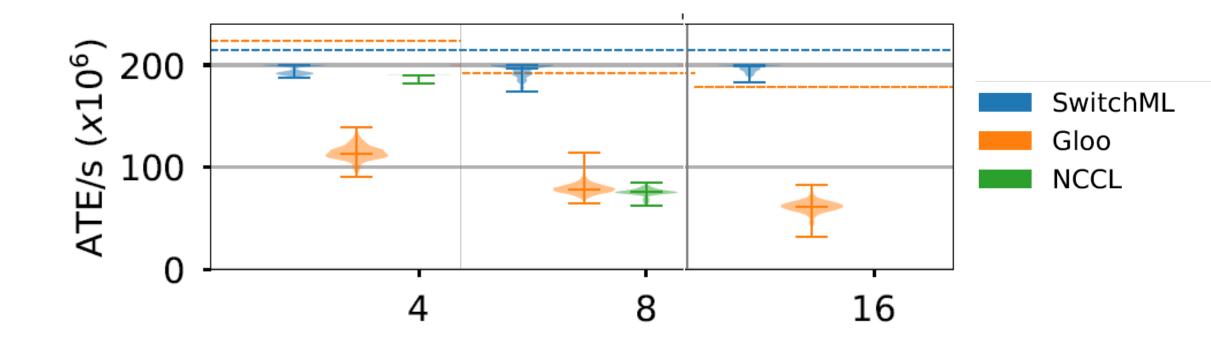
How much faster is SwitchML?

SwitchML provides a speedup from 20% to 300% compared to Tensorflow/NCCL (with direct GPU memory access)



How does SwitchML scale with the number of workers?

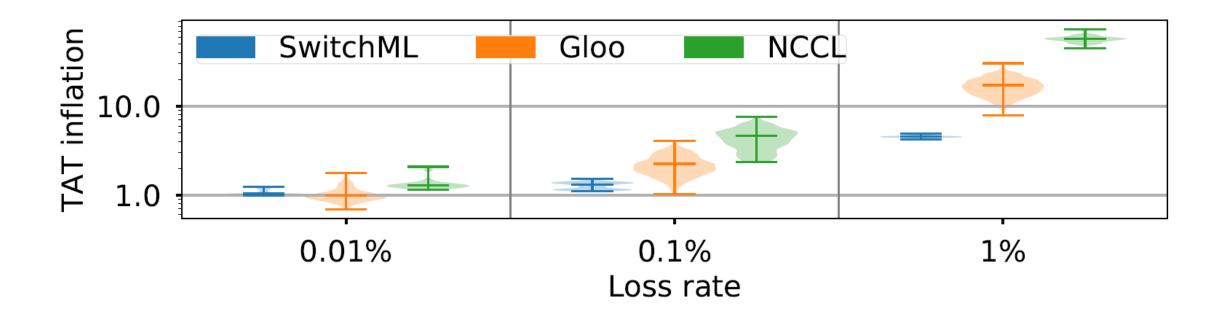
SwitchML performance does not depend on the number of workers



How does SwitchML perform with packet losses?

SwitchML has a lower inflation than TCP

Reasonable packet loss rates have no impact on performance

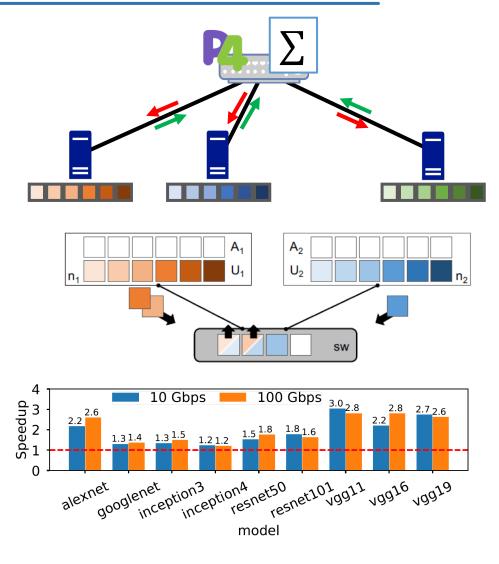


Future work

- Multi-rack
 - Can we use multiple switches to implement hierarchical SwithML?
- Multiple jobs, multiple tenants
 - Can we support the multiple jobs in the same rack by partitioning slots?
- Better numeric representations
 - Can we quantize without having to choose a scaling factor?
- More data per packet
 - Full MTU packets would provide ~31% better performance.

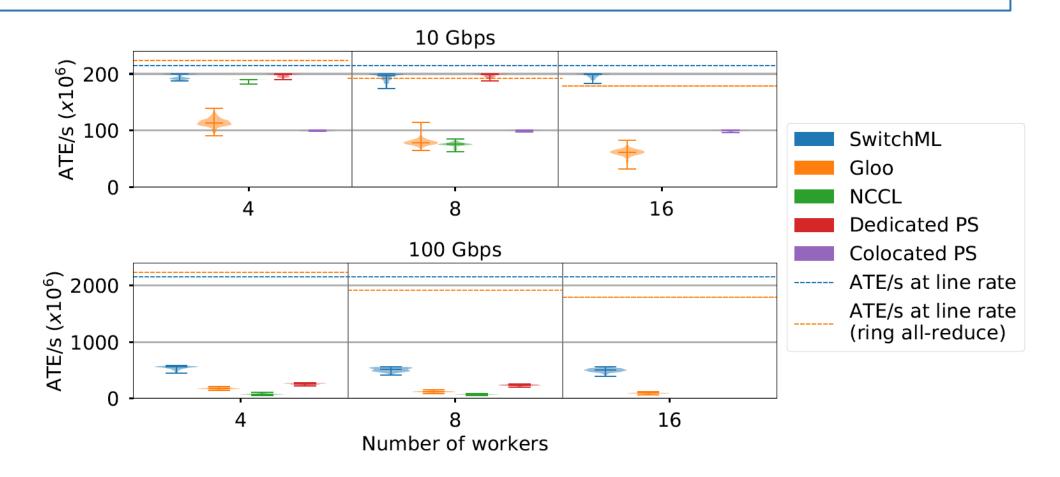
Summary

- SwitchML uses **in-network aggregation** to synchronize model updates
 - Reduce network traffic volume and latency
- SwitchML speeds up training up to 300% with real-world DNN benchmarks
- Aggregation time does not depend on the number of workers
- Preprint on arXiv: <u>https://aka.ms/switchml</u>

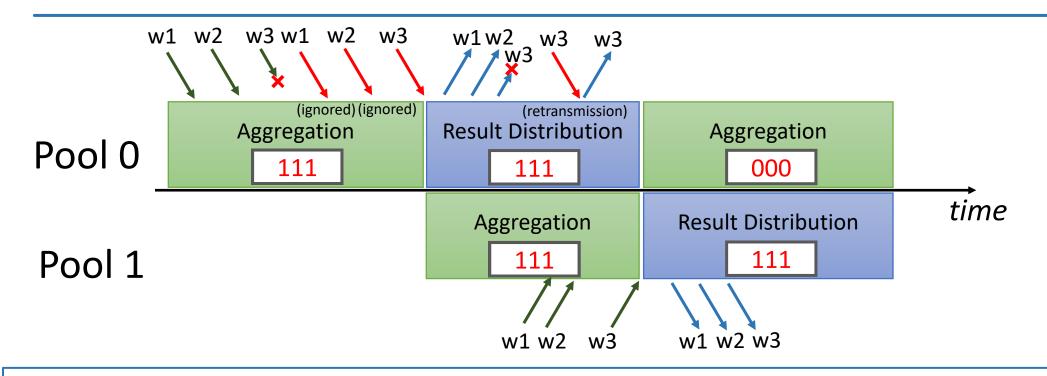


How does SwitchML scale with the number of workers?

SwitchML performance does not depend on the number of workers

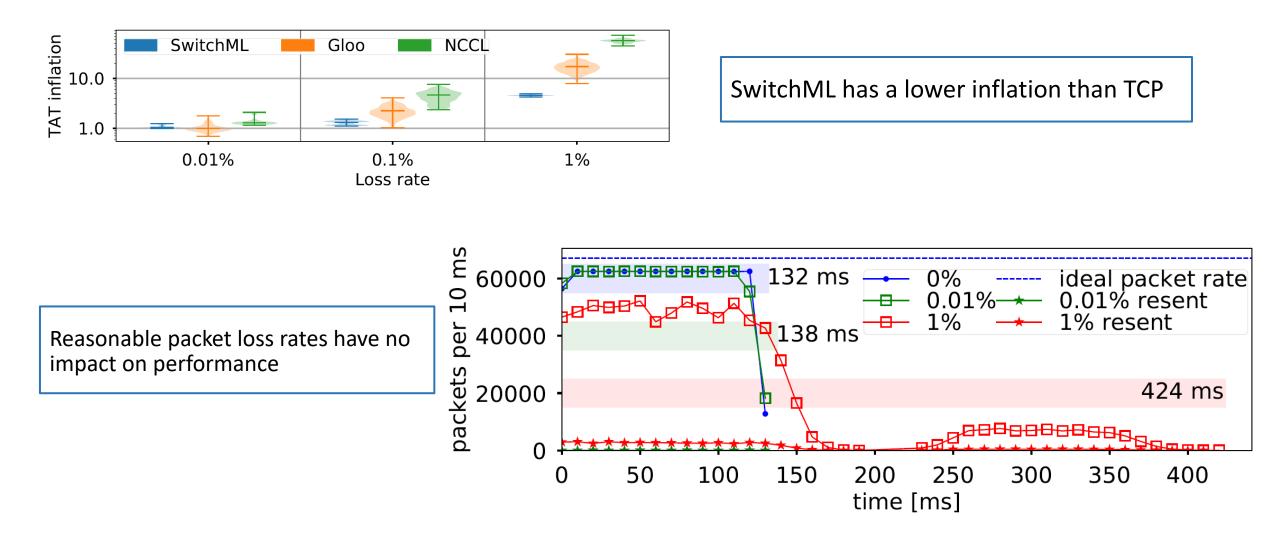


Packet loss tolerance



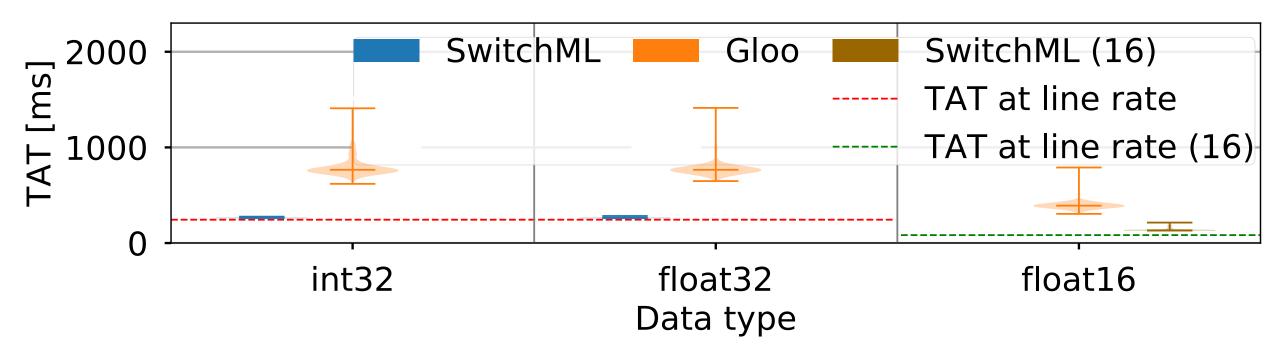
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How does SwitchML perform with packet losses?



Does quantization affects aggregation speed?

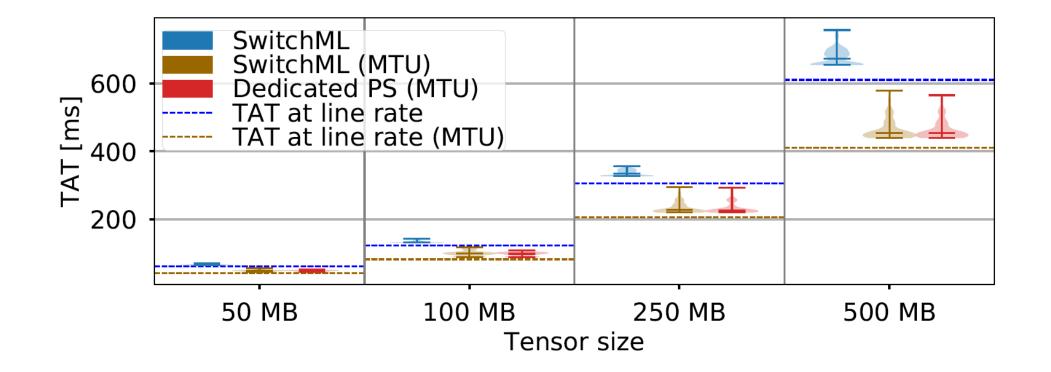
Tensor Aggregation Time unaffected by quantization thanks to AVX instructions



How much does packet size affect performance?

SwitchML reaches line rate with small packets

Would have ~30% better performance if the switch could support MTU-sized packets



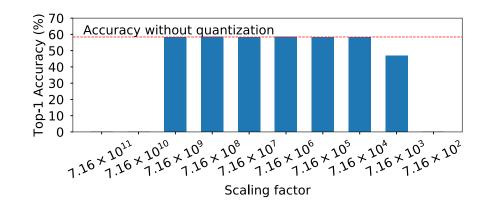
Quantization

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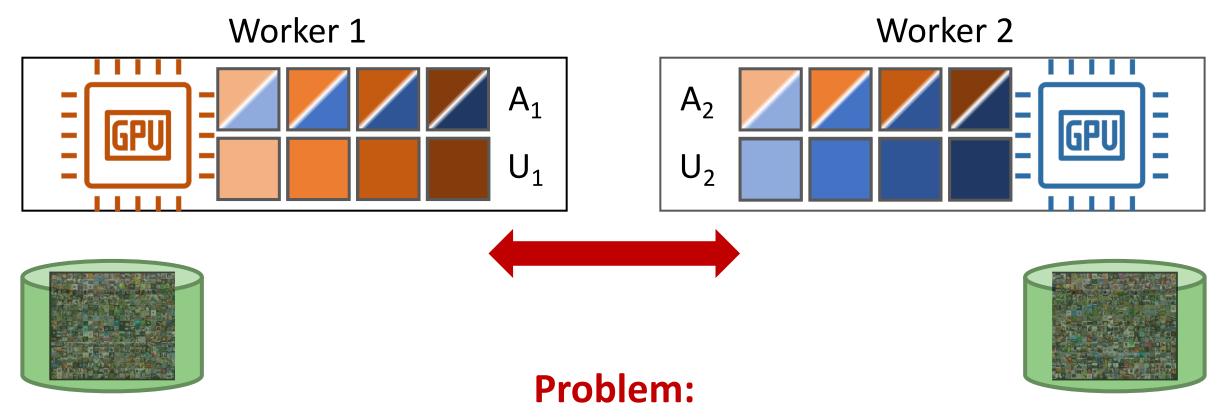
$$\widetilde{U_j^i} = round(sf * U_j^i) \qquad \widetilde{A_j^i} = A_j^i/sf$$

- 32-bit floating point \leftrightarrow 32-bit fixed point conversion \rightarrow At workers with AVX instructions
- 16-bit floating point \leftrightarrow 32-bit fixed point conversion \rightarrow Directly in the switch
 - Scaling is still done by the worker using AVX instructions

This quantization allows training to similar accuracy in a similar number of iterations as an unquantized network for a large range of scaling factors



Aggregation is communication-intensive



Very intensive communication in all-to-all fashion! Network increasingly the bottleneck to training speed